

# TRANSMISSION MECHANISM FOR DRIVING FOUR WHEELS

## BACKGROUND OF THE INVENTION

### 1. Field of the Invention

[0001] The present invention relates to a transmission mechanism of automotive vehicles, and more particularly to a transmission mechanism for driving four wheels.

### 2. Description of the Related Art

[0002] Many transmission mechanisms with a differential gear lock limiting mechanism have been used in automotive vehicles. Because when an automotive vehicle encounters weaker roads, such as loose soil, foothill and the like, two wheels of the automotive vehicle at the same side may lose adhesions to the ground, which will cause the wheels skidding. The differential gear lock limiting mechanism can limit different rotating speeds of the two wheels up to locking the differential gear of the automotive vehicle. In this case, however, the driving side shafts of the two sides will be integrated, and the automotive vehicle can only be driven in line. Moreover, the differential gear lock limiting mechanism used in the art is complicated, expensive and difficult to maintain.

[0003] Hence, a transmission mechanism that overcomes the above-mentioned problems is desired.

## SUMMARY OF THE INVENTION

[0004] Accordingly, an object of the present invention is to provide a transmission mechanism that overcomes the shortcomings in the prior art.

[0005] In order to achieve the above-mentioned object, a transmission mechanism for driving four wheels of an automotive vehicle in accordance with the present invention comprises a drive housing having a first bearing bracket disposed at the middle portion thereof, a second

bearing bracket disposed at the middle portion thereof, a third bearing bracket disposed at the left upper portion thereof, a fourth bearing bracket disposed at the right upper portion thereof, a fifth bearing bracket disposed below the first bearing bracket, and a sixth bearing bracket disposed at the lower portion thereof; a differential mechanism including a right side bevel gear, a left side bevel gear, and a ring gear; a driving power input shaft mounted within the first bearing bracket; a first dual tandem gear slidably mounted on the driving power input shaft; a core shaft mounted within the second bearing bracket, on which the differential mechanism is mounted; a sixth gear connected with the core shaft; a seventh gear connected with the core shaft; a rear right wheel output shaft mounted within the third bearing bracket; an eighth gear fixed to the rear right wheel output shaft; a rear left wheel output shaft mounted within the fourth bearing bracket; a ninth gear fixed to the rear left wheel output shaft; a middle shaft mounted within the fifth bearing bracket; a left gear mounted on the middle shaft close to the fifth bearing bracket; a right gear mounted on the middle shaft to mesh with the ring gear; a middle gear mounted on the middle shaft between the left and the right gear; a front right wheel output shaft mounted within the sixth bearing bracket; a clutch gear mounted on the front right wheel output shaft; a tenth gear mounted on the front right wheel output shaft; and a front left wheel output shaft connected with the tenth gear, into which the front right wheel output shaft is extended. When the driving power input shaft is driven, the first dual tandem gear can be regulated to mesh with either the left gear or the middle gear so that the automotive vehicle can obtain different speeds, and wheels at the same side of the automotive vehicle can be driven at the same time.

**[0006]** In one embodiment of the present invention, the tenth gear is fixed to a shaft sleeve that is mounted on the front right wheel output shaft, and a slidable engaging member is provided to connect the front left wheel output shaft with the shaft sleeve.

**[0007]** In another embodiment carrying out the present invention, a fork sleeve is provided be slidably mounted on the front right wheel output shaft and provides an inner gear to mesh with the clutch gear.

[0008] In still another embodiment of the invention, the ring gear is fixed to a first shaft sleeve extended from the differential case, and the seventh gear is splined to a second shaft sleeve extended from the right side bevel gear.

5 [0009] In the present invention, the first dual tandem gear may be splined to the driving power input shaft, and each of the first dual tandem gear and the slidable engaging member provides a recess at the outer surface thereof for connecting a fork for the control.

[0010] Compared to the prior art, a single differential mechanism is used in the transmission mechanism of the present invention to drive four wheels. Therefore, the transmission mechanism is of a compact structure and a relatively less cost of manufacturing, and makes a clearance  
10 between the chassis of the automotive vehicle and the ground increased. As a result, the performance of the automotive vehicle is improved and the automotive vehicle can be steered smoothly. Furthermore, the single differential mechanism of the invention may generate different speeds between the left side wheels and the right side wheels, and can obtain the same performance as those with two differential mechanisms in the prior art.

15 [0011] Other objects, features and advantages of the present invention will become apparent from the following detailed description in conjunction with the accompanying drawings.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0012] FIG. 1 is a schematic plan view of a transmission mechanism in accordance with the present invention;

20 [0013] FIG. 2 is a schematic and sketching side view showing the location of shafts of the transmission mechanism as shown in FIG. 1; and

[0014] FIG. 3 is a schematically exploded view of a transmission mechanism in accordance with the present invention as shown in FIG 1.

## DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS OF THE INVENTION

[0015] The present invention will be further described below with reference to the drawings.

Referring to FIGs. 1 to 3, a transmission mechanism 100 of an automotive vehicle for driving  
5 four wheels in accordance with the present invention comprises a drive housing 24, a driving  
power input shaft 1, a core shaft 10, a rear right wheel output shaft 9, a rear left wheel output  
shaft 12, a middle shaft 22, a front right wheel output shaft 14, a front left wheel output shaft 19,  
and a differential mechanism 5 mounted at the middle portion of the drive housing 24. The  
differential mechanism 5 includes a right side bevel gear 6, a left side bevel gear 4, a ring gear 3,  
10 a differential case 503 and planetary gears 505. The drive housing 24 has a first bearing bracket  
241 disposed at the middle portion thereof, a second bearing bracket 242 disposed at the middle  
portion thereof, a third bearing bracket 243 disposed at the left upper portion thereof, a fourth  
bearing bracket 244 disposed at the right upper portion thereof, a fifth bearing bracket 245  
disposed below the first bearing bracket 241, and a sixth bearing bracket 246 disposed at the  
15 lower portion thereof.

[0016] The driving power input shaft 1 is connected with an engine (not shown) of the  
automotive vehicle, and mounted within the first bearing bracket 241 and a seventh bearing  
bracket 301 which is disposed within a first shaft sleeve 501 extended from the differential case  
503. A first dual tandem gear 2 having a first larger gear 203 and a first smaller gear 201 is  
20 slidably mounted on the input shaft 1 via a first spline 207.

[0017] Elements of the differential mechanism 5 used in this invention are the same as those in  
the prior art except those specifically described herein. The core shaft 10 is mounted within the  
second bearing bracket 242 and coaxial with the driving power input shaft 1. The right side  
bevel gear 6 and the left side bevel gear 4 are mounted on the core shaft 10, and both of them can  
25 mesh with the planetary gears 505. A sixth gear 11 is mounted to the core shaft 10 via a second  
spline 117. A seventh gear 7 is mounted to a second shaft sleeve 601 extended from the right  
side bevel gear 6 via a third spline 707.

[0018] The rear right wheel output shaft 9 is connected with a rear right wheel (not shown) of the automotive vehicle via a first connecting member 91 and is mounted within the third bearing bracket 243. An eighth gear 8 is mounted on the rear right wheel output shaft 9 via a fourth spline 807 to mesh with the sixth gear 11.

5 [0019] The rear left wheel output shaft 12 is connected with a rear left wheel (not shown) of the automotive vehicle via a second connecting member 121 and mounted within the fourth bearing bracket 244. A ninth gear 13 is mounted on the rear left wheel output shaft 12 via a fifth spline 137 to mesh with the seventh gear 7.

[0020] The middle shaft 22 is mounted within the fifth bearing bracket 245. A left gear 23  
10 and a middle gear 21 are mounted on the middle shaft 22 via a sixth spline 237 and a seventh spline 217, respectively, so that they can mesh with the first larger gear 203 and the first smaller gear 201 of the first dual tandem gear 2, respectively. A right gear 20 is mounted on the middle shaft 22 via an eighth spline 207 to mesh with the ring gear 3.

[0021] The front right wheel output shaft 14 is mounted within the sixth bearing bracket 246  
15 and extended into the front left wheel output shaft 19. A clutch gear 16 having a second larger gear 163 and a second smaller gear 161 is mounted on the front right wheel output shaft 14 via roller bearings 167, 169. A fork sleeve 15 is slidably splined to the front right wheel output shaft 14 and provides an inner gear 153 that can mesh with the second smaller gear 161. A tenth gear 17 is fixed to a shaft sleeve 171 that is connected with the shaft 19 by a slidable engaging  
20 member 18. The second larger gear 163 meshes with the sixth gear 11.

[0022] Recesses 205, 151 and 181 are provided at the outer surface of the first dual tandem gear 2, the fork sleeve 15 and the slidable engaging member 18, respectively, to accommodate forks (not shown) that extend out of the drive housing 24.

[0023] The operation of the transmission mechanism 100 of the present invention for driving  
25 four wheels of an automotive vehicle will now be described as follows. The driving power is transmitted to the driving power input shaft 1 to drive the first dual tandem gear 2 to rotate. The

first dual tandem gear 2 can be regulated to mesh with either the middle gear 21 with the first smaller gear 201 or the left gear 23 with the first larger gear 203 so that the right gear 20 rotates at the different speeds together with the middle shaft 22.

5 [0024] Thus, the ring gear 3 of the differential mechanism 5 engaged to the middle shaft 22 drives the differential mechanism 5 to rotate. This causes the right side bevel gear 6 and the left side bevel gear 4 to rotate. The driving power through the differential mechanism 5 is divided into two parts. The part of the driving power through the right side bevel gear 6 is further divided into two subparts. One subpart is transmitted to the rear left wheel output shaft 12 via the seventh gear 7 and the ninth gear 13. Another subpart is transmitted to the slidable engaging member 18 via the seventh gear 7 and the tenth gear 17, and then transmitted to the front left wheel output shaft 19.

15 [0025] The part of the driving power through the left side bevel gear 4 is transmitted to the core shaft 10 to the sixth gear 11 that drive both the eighth gear 8 and the clutch gear 16 to rotate. The eighth gear 8 then drives the rear right wheel that is connected with the rear right wheel output shafts 9. The front right wheel output shaft 14 that is connected with the front right wheel is driven to rotate via the fork sleeve 15. As a result, the two front output shafts 14, 19 are driven by the fork sleeve 15 and the engaging members 18, respectively, and the two rear output shafts 9, 12 are driven in parallel. With the transmission mechanism 100 of the present invention, the wheels at the same side can be driven at the same time.

20 [0026] When an automotive vehicle equipped the transmission mechanism of the invention moves on weaker roads, and a wheel skids and loses the adhesion to the ground, the output power of the engine will not decrease because the skidding wheel doesn't rotate. Meanwhile, another unskidding wheel at the same side can still be driven because the two wheels are controlled by the same side bevel gear. In addition, because other two wheels at the other side are controlled by another side bevel gear, the vehicle can run as normally. As a result, when two wheels at the same side skid, the vehicle can move via other two unskidding wheels at the same side, and when

25

two wheels at the different sides skid, the automotive vehicle can move via other two unskidding wheels at the different sides.

[0027] It is understood that the particular structures embodying the present invention shown and described above are only used for illustrating the present invention, and are not intended to  
5 limit the invention. Any modifications or variations to the present invention without departing from the spirit of the invention shall be fallen into the scope of the invention defined by the appended claims.